Maps

- Definitions what is a map (or function)?
- Specification
- List-based representation (singly linked)
- Sorted block representation

Reading: Weiss, Section 6.8

What is a Map (or Function)?

Some definitions...

relation — set of *n*-tuples

eg. { $\langle 1, i, a \rangle$, $\langle 2, ii, b \rangle$, $\langle 3, iii, c \rangle$, $\langle 4, iv, d \rangle$, ...}

binary relation — set of pairs (2-tuples)

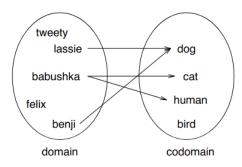
eg. $\{\langle lassie, dog \rangle, \langle babushka, cat \rangle, \langle benji, dog \rangle, \langle babushka, human \rangle, \ldots \}$

 \mathbf{domain} — set of values which can be taken on by the first item of a binary relation

eg. {lassie, babushka, benji, felix, tweety}

codomain — set of values which can be taken on by the second item of a binary relation

eg. $\{dog, cat, human, bird\}$



dog is called the \mathbf{image} of lassie under the relation

map (or function) — binary relation in which each element in the domain is mapped to *at most one* element in the codomain (*many-to-one*)

eg.

Affiliation = $\{$	<	Turing	,	Manchester	\rangle
	<	Von Neumann	,	Princeton	\rangle
	<	Knuth	,	Stanford	\rangle
	<	Minsky	,	MIT	\rangle
	(Dijkstra	,	Texas	Ì
	Ś	McCarthy	,	Stanford	\rangle

Shorthand notation: eg. affiliation(Knuth) = Stanford

partial map — not every element of the domain has an image under the map (ie, the image is undefined for some elements)

Aside: Why Study Maps?

A Java method is a function or map — why implement our own map as an ADT?

- Create, modify, and delete maps during use.
- a map of affiliations may change over time Turing started in Cambridge, but moved to Manchester after the war.

A Java program cannot modify itself (and therefore its methods) during execution (some languages, eg Prolog, can!)

• Java methods just return a result — we want more functionality (eg. ask "is the map defined for a particular domain element?")

Map Specification

1. Constructor

2. Map(): create a new map that is undefined for all domain elements.

3. Checkers

- 4. *isEmpty()*: return *true* if the map is empty (undefined for all domain elements), *false* otherwise.
- 5. isDefined(d): return true if the image of d is defined, false otherwise.

6. Manipulators

- 7. assign(d,c): assign c as the image of d.
- 8. image(d): return the image of d if it is defined, otherwise throw an exception.
- 9. deassign(d): if the image of d is defined return the image and make it undefined, otherwise throw an exception.

List-based Representation

A map can be considered to be a list of pairs. Providing this list is *finite*, it can be implemented using one of the techniques used to implement the list ADT.

Better still, it can be built using the list ADT!

(Providing it can be done efficiently — recall the example of *overwrite*, using *insert* and *delete*, in a text editor based on the list ADT.)

Question: Which List ADT should we use?

- Require arbitrarily many assignments.
- Do we need *previous*?

 $Implementation \dots$

```
public class MapLinked {
  private ListLinked list;
  public MapLinked () {
    list = new ListLinked();
  }
```

}

We said a (finite) map could be considered a list of pairs — need to define a Pair object. . .

```
public class Pair {
  public Object item1; // the first item (or domain item)
  public Object item2; // the second item (or codomain item)
  public Pair (Object i1, Object i2) {
    item1 = i1;
    item2 = i2;
    }
```

Example — Implementation of *image*

```
public Object image (Object d) throws ItemNotFound {
  WindowLinked w = new WindowLinked();
  list.beforeFirst(w);
  list.next(w);
  while (!list.isAfterLast(w) &&
       !((Pair)list.examine(w)).item1.equals(d) ) list.next(w);
  if (!list.isAfterLast(w)) return ((Pair)list.examine(w)).item2;
  else throw new ItemNotFound("no image for object passed");
}
```

Notes:

- 1. !list.isAfterLast(w) must precede list.examine(w) in the condition for the loop — why??
- 2. Note use of parentheses around casting so that the field reference (eg .item1) applies to the cast object (Pair rather than Object).
- 3. Assumes appropriate *equals* methods for each of the items in a pair.

Performance

Map and is Empty make trivial calls to constant-time list ADT commands. The other four operations all require a sequential search within the list \rightarrow linear in the size of the defined domain (O(n))

Performance using (singly linked) List ADT

Operation	
Map	1
is Empty	1
is Defined	n
assign	n
image	n
deassign	n

If the maximum number of pairs is predefined, and we can specify a total ordering on the domain, better efficiency is possible...

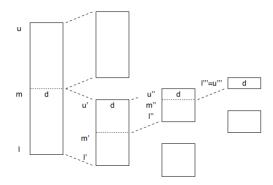
Sorted-block Representation

Some of the above operations take linear time because they need to search for a domain element. The above program does a linear search.

Q: Are any more efficient searches available for arbitrary *linked* list?

Binary Search

An algorithm for binary search...



Assume block is defined as:

private Pair[] block;

Then binary search can be implemented as follows...

```
protected int bSearch (Object d, int l, int u) {
    if (l == u) {
        if (d.toString().compareTo(block[l].item1.toString()) == 0)
            return l;
    else return -1;
    }
    else {
        int m = (l + u) / 2;
        if (d.toString().compareTo(block[m].item1.toString()) <= 0)
            return bSearch(d,l,m);
        else return bSearch(d,m+1,u);
    }
}</pre>
```

Note: compareTo is an instance method of String — returns 0 if its argument matches the String, a value < 0 if the String is lexicographically less than the argument, and a value > 0 otherwise.

Exercise: Can **bSearch** be implemented using only the abstract operations of the list ADT?

Performance of Binary Search

One way of looking at the problem, to get a feel for it, is to consider the biggest list of pairs we can find a solution for with m calls to **bSearch**.

Calls to bSearch	Size of list
1	1
2	1 + 1
3	2 + 1 + 1
4	4 + 2 + 1 + 1
:	
m	$(2^{m-2} + 2^{m-3} + \dots + 2^1 + 2^0) + 1$
	$= (2^{m-1} - 1) + 1$
	$=2^{m-1}$

It can be shown (see Exercises) that T_n is $O(\log n)$.

Comparative Performance of Operations

is Defined and image simply require binary search, therefore they are $O(\log n)$ — much better than singly linked list representation.

However, since the block is sorted, both *assign* and *deassign* may need to move blocks of items to maintain the order. Thus they are

$$\max(O(\log n), O(n)) = O(n).$$

In summary...

Operation	Linked List	Sorted Block
Map	1	1
is Empty	1	1
is Defined	n	$\log n$
assign	n	n
image	n	$\log n$
deassign	n	n

Sorted block may be best choice if:

- 1. map has fixed maximum size
- 2. domain is totally ordered
- 3. map is fairly static mostly reading (*isDefined, image*) rather than writing (*assign, deassign*)

Otherwise linked list representation is probably better.

Summary

- A map (or function) is a many-to-one binary relation.
- Implementation using linked list
 - can be arbitrarily large
 - reading from and writing to the map takes linear time
- Sorted block implementation
 - fixed maximum size
 - requires ordered domain
 - reading is logarithmic, writing is linear